

Data-Driven Computation of Probabilistic Marching Cubes for Efficient Visualization of Level-Set Uncertainty

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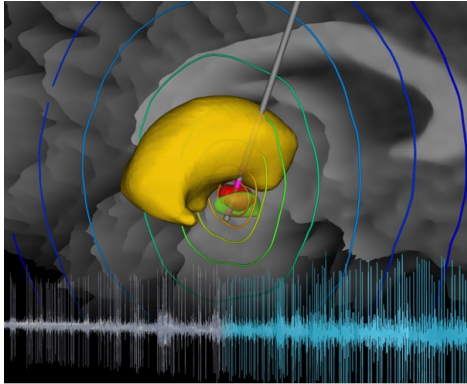
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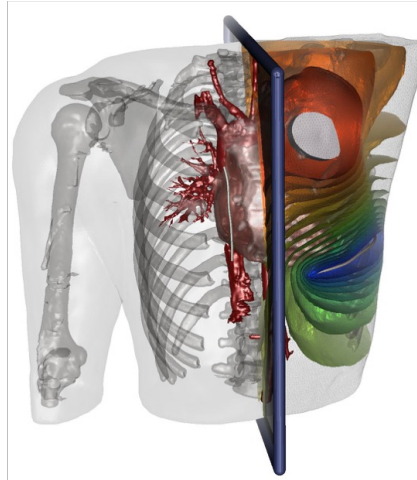
EuroVis 2024 Short Papers



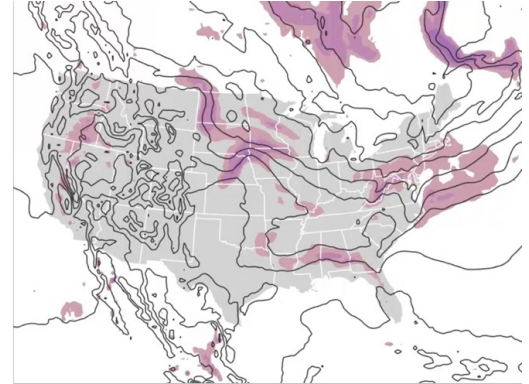
Level-Set Visualization



Deep Brain Stimulation (DBS)



Bioelectric-field Simulation

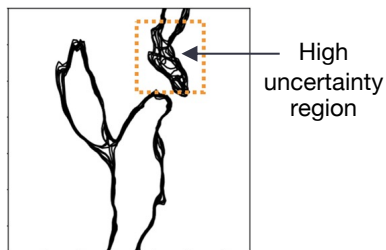


Temperature Field

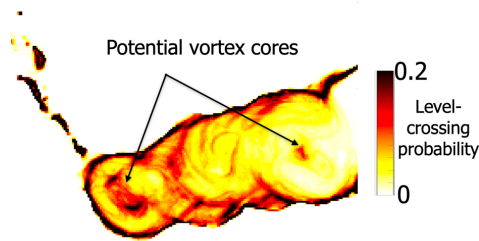
Uncertainty Visualization of Level-Sets



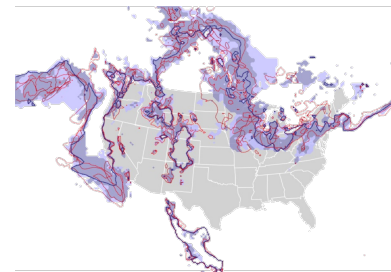
Uncertainty in data arises from various factors, including quantization errors, approximations used in simulations, model uncertainty etc.



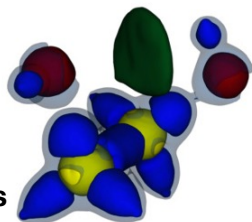
Spaghetti plot (climatology)
[Potter et al., 2009]



Probabilistic marching cubes (oceanology)
[Pöthkow et al., 2011,
Athawale et al., 2021]

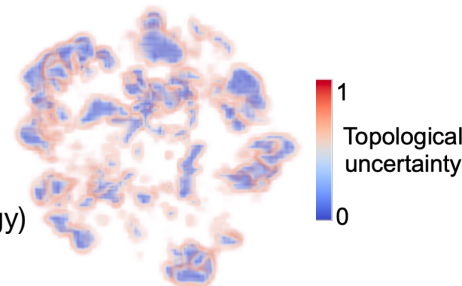


Contour/surface boxplots (climatology)
[Whitaker et al., 2013, Genton et al., 2014]



Feature confidence level-sets
(Molecular dynamics)
[Sane et al., 2020]

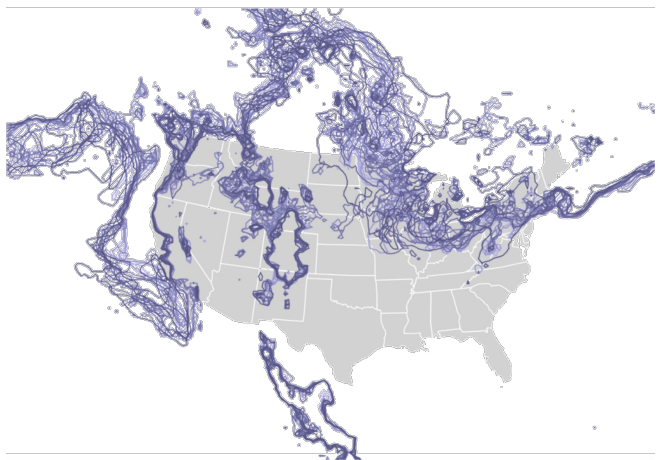
Fiber uncertainty (cosmology)
[Athawale et al., 2022]



Probabilistic Marching Cubes

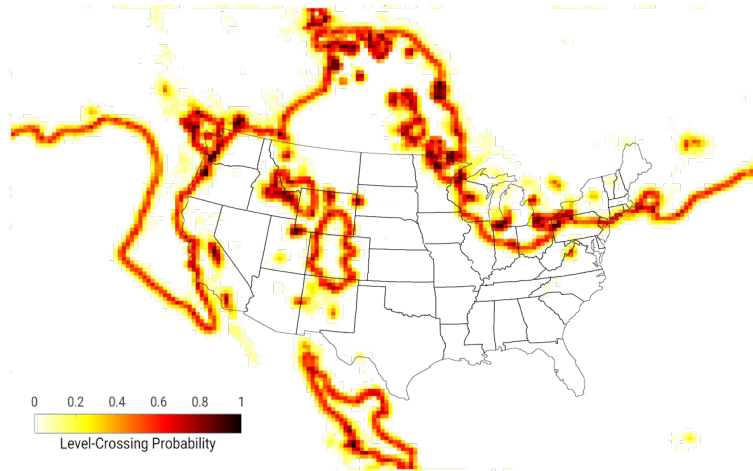


Spaghetti plot
[Potter et al., 2009]



- + Computationally efficient
- + Direct display of high/low uncertainty among isocontours
- Clutter and occlusion (severe in 3D)

Probabilistic marching cubes
[Pöthkow et al., 2011, Athawale et al., 2021]



- + Mitigates occlusion/clutter
- + Highlights high probability (red) isocontour regions
- **Computationally expensive** (because of the required Monte Carlo sampling)

Probabilistic Marching Cubes

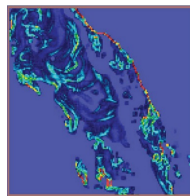


Problem: Computational cost of probabilistic marching cubes limits its use and prevents its integration with visualization tools/software (e.g., ParaView, VisIt)

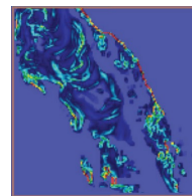
Existing Solutions:

Acceleration by Deep Learning (Han et al., 2022)

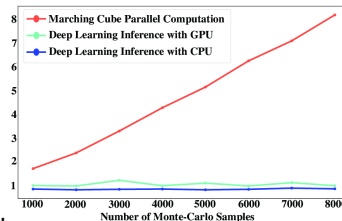
Up to 170× speedup, but requires training and limited to time-varying ensembles



Monte Carlo

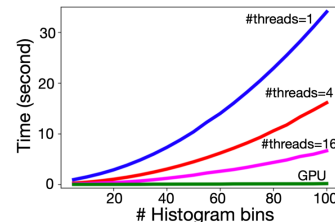
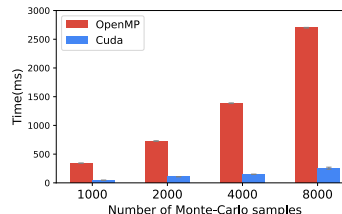


Machine-predicted



FunMC² filter: Acceleration using Many-Core GPUs (Wang et al., 2023)

Up to 396× speedup, but requires access to the GPU resources



Probabilistic Marching Cubes

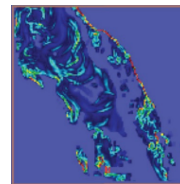
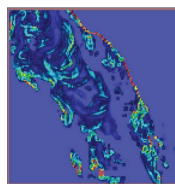


Problem: Computational cost of probabilistic marching cubes limits its use and prevents its integration with visualization tools/software (e.g., ParaView, VisIt)

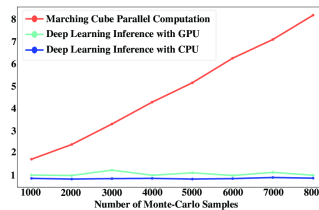
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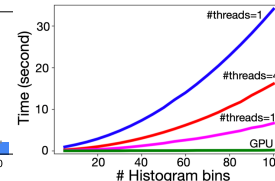
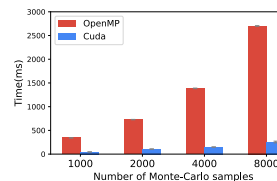


Monte Carlo Machine-predicted



FunMC² filter: Acceleration using Many-Core GPUs

(Wang et al., 2023) Up to 396× speedup, but requires access to the GPU resources



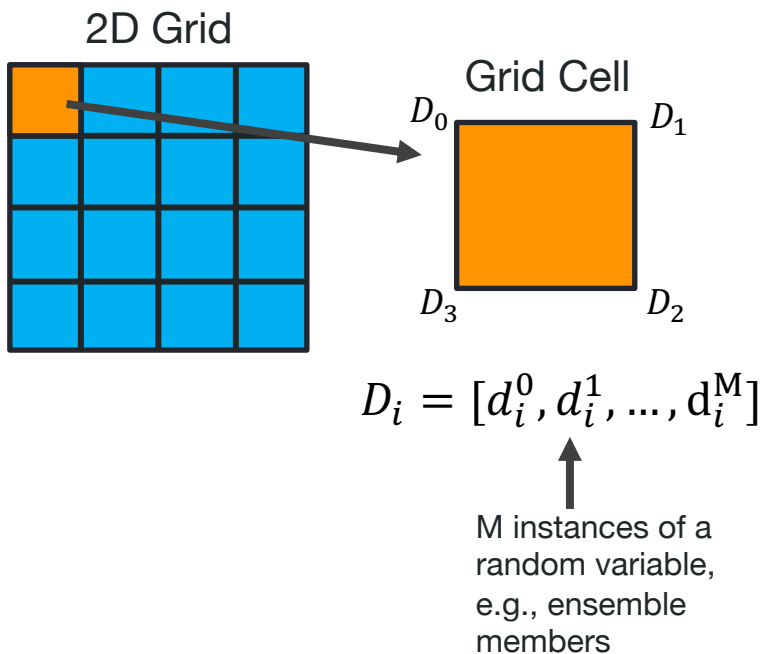
Our Contribution:

Data-driven methods (e.g., dimensionality reduction and correlation analysis) to reduce the amount of Monte Carlo sampling, and hence, achieve speedup

Probabilistic Marching Cubes



[Pöthkow et al., 2011, Athawale et al., 2021]



Uncertainty modeling with multivariate Gaussian distribution, i.e., $\mathcal{N}(\mu, cov)$

Means: $\mu_i = \frac{1}{M} \sum_{m=1}^M d_i^m$

Covariance Matrix:

$$cov_{i,j} = \frac{1}{M-1} \sum_{m=1}^M (d_i^m - \mu_i)(d_j^m - \mu_j)$$

where $i, j = 0, 1, 2, 3$

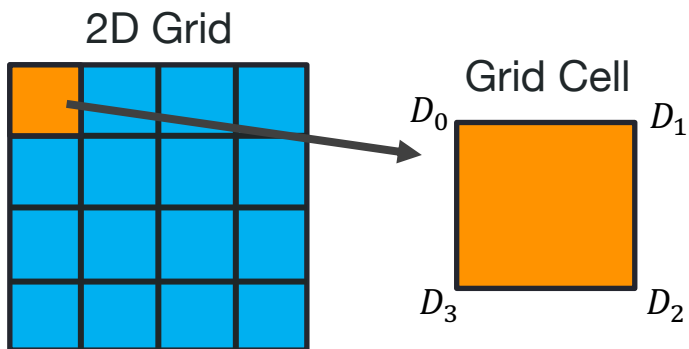
Draw S Monte Carlo samples from $\mathcal{N}(\mu, cov)$

Level-crossing probability $LCP = \frac{C}{S}$ if a level-set passes through C samples in a cell

Probabilistic Marching Cubes



[Pöthkow et al., 2011, Athawale et al., 2021]



$$D_i = [d_i^0, d_i^1, \dots, d_i^M]$$

!! Sampling a 4D space is computationally expensive →

(Each multivariate Gaussian sample is 4D representing data at four vertices of a grid cell)

Uncertainty modeling with multivariate Gaussian distribution, i.e., $\mathcal{N}(\mu, cov)$

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Covariance Matrix:

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where $i, j = 0, 1, 2, 3$

Draw S Monte Carlo samples from $\mathcal{N}(\mu, cov)$

Level-crossing probability $LCP = \frac{C}{S}$ if a level-set passes through C samples in a cell



We optimize this step to
reduce the level of sampling
and speedup computations



Draw S Monte Carlo samples from $\mathcal{N}(\mu, cov)$

Level-crossing probability $LCP = \frac{C}{S}$ if a level-set
passes through C samples in a cell

(1) Eigenvalue decomposition technique

- Extract important *low-dimensional* structures (e.g., top eigenvalues)
- Perform sampling in a low-dimensional space (reduces the level of sampling)

(2) Adaptive probability model

- If *strong* correlation, use multivariate Gaussian sampling
- If *weak* correlation, use closed-form independent Gaussian models [Pöthkow et al., 2011, Athawale et al., 2021] (Closed-form solutions do not require sampling and are faster)

Eigenvalue Decomposition Technique



| N-D sample $\mathbf{D} \sim \mathcal{N}(\boldsymbol{\mu}, \text{cov})$ | Mean $\boldsymbol{\mu}$ | Eigenvectors Eigenvalue decomposition of cov | Eigenvalues | Standard Normal Distribution (i.e., $\mathbf{Z}_i \sim \mathcal{N}(0, 1)$) |
|---|--|--|--|--|
| $\begin{bmatrix} D_1 \\ \vdots \\ D_n \end{bmatrix}$ | $\begin{bmatrix} \mu_1 \\ \vdots \\ \mu_n \end{bmatrix}$ | $\begin{bmatrix} \vec{V}_{11} & \dots & \vec{V}_{n1} \\ \vdots & \ddots & \vdots \\ \vec{V}_{1n} & \dots & \vec{V}_{nn} \end{bmatrix}$ | $\begin{bmatrix} \lambda_1^{\frac{1}{2}} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n^{\frac{1}{2}} \end{bmatrix}$ | $\begin{bmatrix} Z_1 \\ \vdots \\ Z_n \end{bmatrix}$ |

$$D_j = \mu_j + \sum_{i=1}^{i=n} \vec{V}_{ij} \lambda_i^{0.5} Z_i$$

Eigenvalue Decomposition Technique



N-D sample
 $\mathbf{D} \sim \mathcal{N}(\boldsymbol{\mu}, \text{cov})$

Mean
 $\boldsymbol{\mu}$

Eigenvectors

Eigenvalue decomposition of cov

Eigenvalues

Standard Normal Distribution
(i.e., $\mathbf{Z}_i \sim \mathcal{N}(\mathbf{0}, \mathbf{1})$)

$$\begin{bmatrix} D_1 \\ \vdots \\ D_n \end{bmatrix} = \begin{bmatrix} \mu_1 \\ \vdots \\ \mu_n \end{bmatrix} + \begin{bmatrix} \vec{V}_{11} & \dots & \vec{V}_{n1} \\ \vdots & \ddots & \vdots \\ \vec{V}_{1n} & \dots & \vec{V}_{nn} \end{bmatrix} \begin{bmatrix} \lambda_1^{\frac{1}{2}} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n^{\frac{1}{2}} \end{bmatrix} \begin{bmatrix} Z_1 \\ \vdots \\ Z_n \end{bmatrix}$$

$$D_j = \mu_j + \sum_{i=1}^{i=n} \vec{V}_{ij} \lambda_i^{0.5} Z_i$$

Our idea: We do not need to loop over all eigenvalues if only a few eigenvalues are significant relative to others

Eigenvalue Decomposition Technique



N-D sample
 $D \sim \mathcal{N}(\mu, cov)$

Mean
 μ

Eigenvectors

Eigenvalue decomposition of cov

Eigenvalues

Standard Normal Distribution
(i.e., $Z_i \sim \mathcal{N}(0, 1)$)

$$\begin{bmatrix} D_1 \\ \vdots \\ D_n \end{bmatrix} = \begin{bmatrix} \mu_1 \\ \vdots \\ \mu_n \end{bmatrix} + \begin{bmatrix} \vec{V}_{11} & \dots & \vec{V}_{n1} \\ \vdots & \ddots & \vdots \\ \vec{V}_{1n} & \dots & \vec{V}_{nn} \end{bmatrix} \begin{bmatrix} \lambda_1^{\frac{1}{2}} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \lambda_n^{\frac{1}{2}} \end{bmatrix} \begin{bmatrix} Z_1 \\ \vdots \\ Z_n \end{bmatrix}$$

$$D_j = \mu_j + \sum_{i=1}^{i=n} \vec{V}_{ij} \lambda_i^{0.5} Z_i$$

Original formula



$$D_j \approx \mu_j + \sum_{i=1}^{i=m} \vec{V}_{ij} \lambda_i^{0.5} Z_i$$

Approximate formula (loop of m significant eigenvalues)

Eigenvalue Decomposition Technique



N-D sample
 $D \sim \mathcal{N}(\mu, cov)$

Mean
 μ

Eigenvectors

Eigenvalue decomposition of cov

Eigenvalues

Standard Normal Distribution
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Original formula

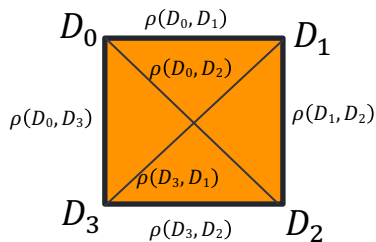


$$D_j \approx \mu_j + \sum_{i=1}^{i=m} \vec{V}_{ij} \lambda_i^{0.5} Z_i$$

Approximate formula (loop of m significant eigenvalues)

Corresponds to sampling of m -D space, and hence, achieves a speedup if $m < n$

Adaptive Probability Model



- Covariance matrix **cov** captures the correlation among data D_i . *What if the data are independent? Can we do better?*

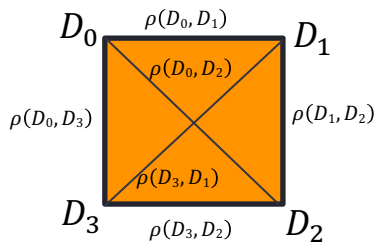
- **Our idea:** Use the Pearson's correlation coefficient (ρ) to adaptively decide a probability model

If $\max[\rho(D_i, D_j)] < 0.2 \forall i, j$ and $i \neq j$
use independent model (no need of sampling, hence faster)

Else

use multivariate Gaussian model (slower) [we use the proposed eigenvalue decomposition approach]

Adaptive Probability Model



- Covariance matrix **cov** captures the correlation among data D_i . *What if the data are independent? Can we do better?*

- **Our idea:** Use the Pearson's correlation coefficient (ρ) to adaptively decide a probability model

If $\max[\rho(D_i, D_j)] < 0.2 \forall i, j$ and $i \neq j$
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Else

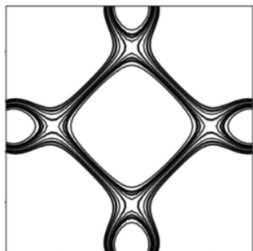
use multivariate Gaussian model (slower) [we use the proposed eigenvalue decomposition approach]

Drawback: Computation of pairwise correlation ρ is costly, but it can be precomputed since it does not depend on the **isovalue**

Results (Synthetic Data): Eigenvalue Decomposition Technique



Ackley Function [Ackley, 1987]



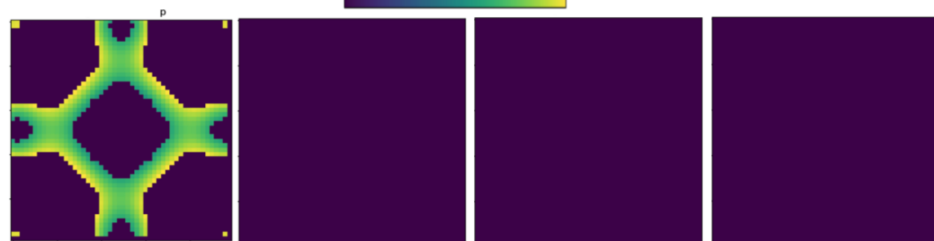
Spaghetti plot (Correlated uncertain data)

0 ρ_{max} 1



Correlation (ρ)

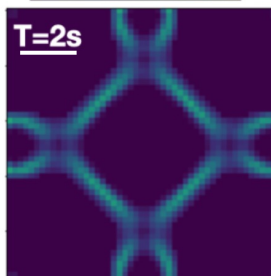
0 eig_max



$\lambda_1 = 89.19$ $\lambda_2 = 0$ $\lambda_3 = 0$ $\lambda_4 = 0$

Eigenvalues (λ) [Most information is in the first eigenvector]

0 LCP 1



PMC (Original)

$$D_j = \mu_j + \sum_{i=1}^{i=n} \vec{v}_{ij} \lambda_i^{0.5} Z_i$$

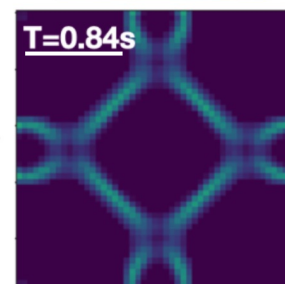
$n=4$



$$D_j \approx \mu_j + \sum_{i=1}^{i=m} \vec{v}_{ij} \lambda_i^{0.5} Z_i$$

$m=1$

0 LCP 1



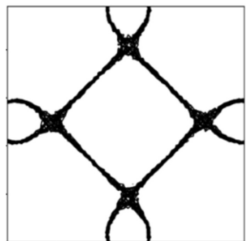
PMC (Eigenvalue-based)

0 Difference 1



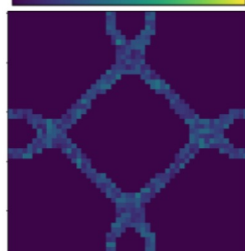
Results (Synthetic Data): Adaptive Probability Model ★ ★ ★

Ackley Function [Ackley, 1987]



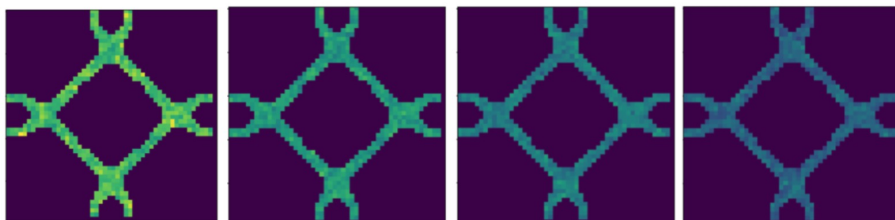
Spaghetti plot (Independent noise)

0 ρ_{max} 1



Correlation

0 eig_max 1



$\lambda_1 = 1.92$

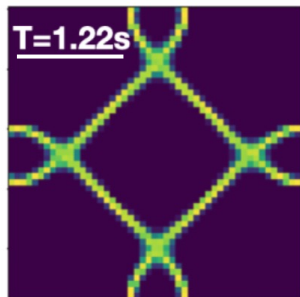
$\lambda_2 = 1.55$

$\lambda_3 = 1.25$

$\lambda_4 = 0.96$

Eigenvalues (λ) [Information is in all eigenvectors]

0 LCP 1

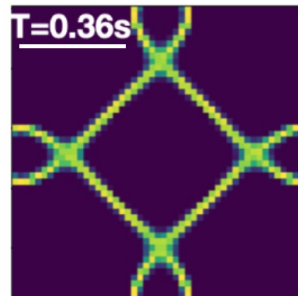


PMC (Original)



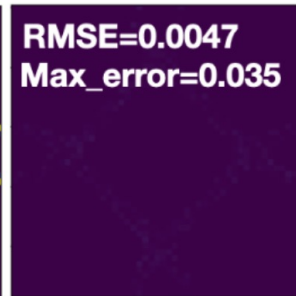
If $\rho_{max} < 0.2$:
Use fast independent
model

0 LCP 1

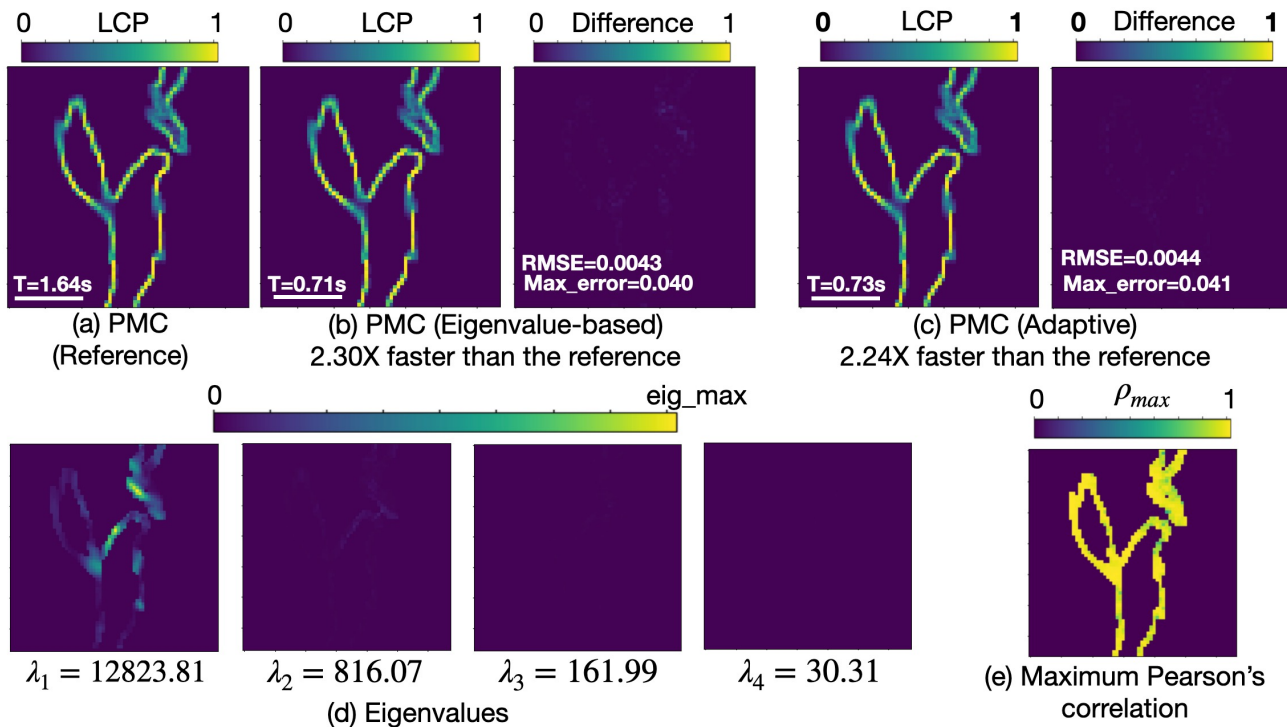


PMC (Adaptive model)

0 Difference 1



Results (Wind Dataset)



- Our proposed methods (b and c) are faster than the original PMC (a)
- Most information is in the first eigenvector
- Highly correlated uncertain data (So the both techniques provide a similar speedup)

Results (Beetle Dataset)

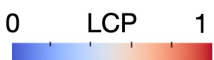


27.18 seconds

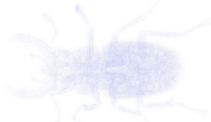


(f) PMC
(Reference)

16.72 seconds

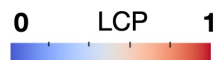


(g) PMC (Eigenvalue-based)
1.63X faster than the reference



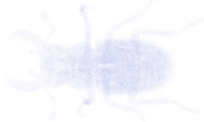
RMSE=0.0028,
Max_error=0.126

17.09 seconds



(h) PMC (Adaptive)

1.59X faster than the reference



RMSE=0.0028,
Max_error=0.130

0 eig_max

| | | | |
|-----------------------------------|-----------------------------------|----------------------------------|----------------------------------|
| $\lambda_1 = 83.31\text{e}+9$ | $\lambda_2 = 22.24\text{e}+9$ | $\lambda_3 = 7.72\text{e}+9$ | $\lambda_4 = 3.50\text{e}+9$ |
| $\lambda_5 = 1.75\text{e}+9$ | $\lambda_6 = 0.94\text{e}+9$ | $\lambda_7 = 0.51\text{e}+9$ | $\lambda_8 = 0.25\text{e}+9$ |

(i) Eigenvalues

0 ρ_{max} 1



(j) Maximum Pearson's
correlation

Correlation precomputation
time on a serial processor:
94.6 minutes

- Our proposed methods (b and c) are faster than the original PMC (a)
- Combined FunMC² [Wang et al., 2023] with our methods on the Frontier supercomputer
- Most information is in the four eigenvector
- Highly correlated uncertain data (So the both techniques provide a similar speedup)

Conclusion and Future Work



- Novel data-driven solutions to reduce computational overhead of uncertainty visualization of level-sets
- *Eigenvalue decomposition* and *adaptive probability model* techniques to make adaptive compute decisions for a faster speed
- Integration with the FunMC² [Wang et al., 2023] filter to demonstrate the speedup on a Frontier supercomputer
- In the future, we will explore more data-driven methods for further acceleration and for various features, e.g., critical points, Morse complexes etc.

Acknowledgements



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